

### Problem 4-4

The tracking phase jitter for the noncoherent delay lock tracking loop is given by

$$\sigma^2 = \frac{\eta \mathcal{W}_L}{2K_d^2}$$

where  $\eta/2$  is the equivalent noise power spectral density at the output of the phase detector.  
From (4-75)

$$\frac{\eta}{2} = \frac{1}{2}(K_1 N_0)^2 B_N + \frac{1}{2} K_1^2 N_0 P \left\{ R_c^2 \left[ \left( \delta - \frac{\Delta}{2} \right) T_c \right] + R_c^2 \left[ \left( \delta + \frac{\Delta}{2} \right) T_c \right] \right\}$$

The autocorrelation functions are evaluated at  $\delta = 0$  to give

$$R_c^2 \left( \pm \frac{\Delta}{2} T_c \right) = \left( 1 - \frac{\Delta}{2} \right)^2$$

Thus,

$$\frac{\eta}{2} = \frac{1}{2} (K_1 N_0)^2 B_N + K_1^2 N_0 P \left( 1 - \frac{\Delta}{2} \right)^2$$

From Fig. 4-13 with  $N \gg 1$ ,

$$K_d = 2K_1 P \left( 1 - \frac{\Delta}{2} \right)$$

Hence

$$\begin{aligned} \sigma^2 &= \frac{\eta \mathcal{W}_L}{2K_d^2} = \left[ \frac{N_0^2 B_N}{8(1 - \Delta/2)^2 P^2} + \frac{N_0 P}{4P^2} \right] \mathcal{W}_L \\ &= \frac{N_0 \mathcal{W}_L}{4P} \left[ 1 + \frac{N_0 B_N}{2P(1 - \Delta/2)^2} \right] = \frac{1}{2\rho_L} \left[ 1 + \frac{1}{2(1 - \Delta/2)^2 \rho_{IF}} \right] \end{aligned}$$

Since the IF bandwidth is 100 times larger than the two-sided loop bandwidth,  $\rho_{IF} = \rho_L/200$  and

$$\sigma^2 = \frac{1}{2\rho_L} \left[ 1 + \frac{100}{2(1 - \Delta/2)^2 \rho_L} \right]$$

### Problem 4-8

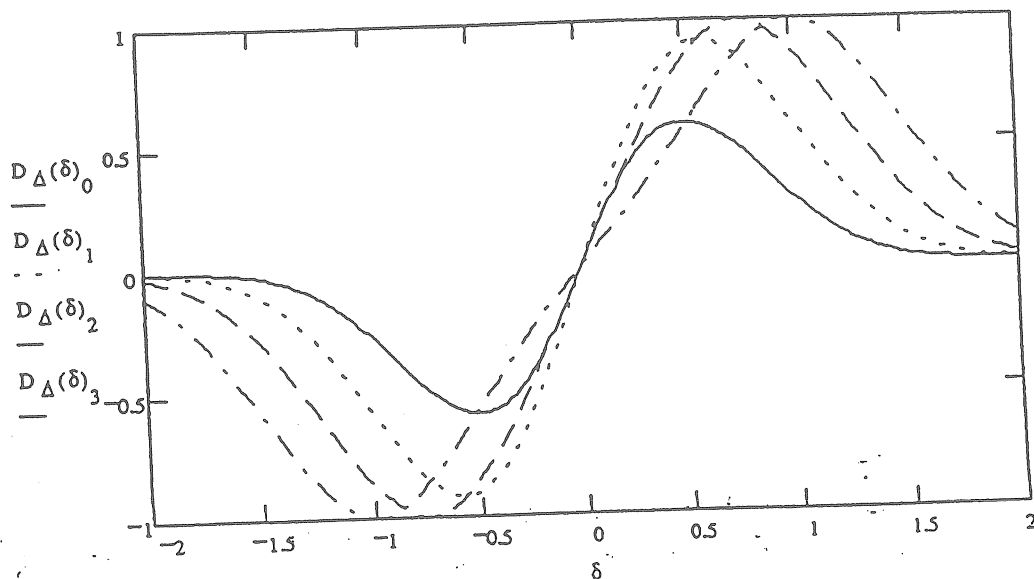
For MSK spreading modulation, the autocorrelation function of the complex envelope is [see (4-141)]

$$R_{\theta}(\tau) = \frac{1}{2\pi} \left[ \pi \left( 1 - \frac{|\tau|}{2T_c} \right) \cos \left( \frac{\pi |\tau|}{2T_c} \right) + \sin \left( \frac{\pi |\tau|}{2T_c} \right) \right]$$

The discriminator function using this autocorrelation function is

$$D_{\Delta}(\delta) = 4R_{\theta}^2 \left[ \left( \delta - \frac{\Delta}{2} \right) T_c \right] - 4R_{\theta}^2 \left[ \left( \delta + \frac{\Delta}{2} \right) T_c \right]$$

This is plotted below for  $\Delta = 0.5$  (solid line), 1.0 (short dashes), 1.5 (long dashes), and 2.0 (alternating short and long dashes).



### Problem 4-11

Equation (4-26) gives the expression for the normalized tracking error:

$$\frac{T_d(s) - \hat{T}_d(s)}{T_c} = \frac{T_d(s)}{T_c} \frac{s^2 + s/\tau_1}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

where

$$\omega_n = \sqrt{K_c g_c / \tau_1} \quad \text{and} \quad \zeta = \frac{\tau_2}{2\omega_n} + \frac{1}{2\tau_1\omega_n}$$

(a) For this case,  $T_d(t)/T_c = A u(t)$  giving  $T_d(s)/T_c = A/s$ . Thus

$$E(s) = \frac{A(s + 1/\tau_1)}{s^2 + 2\zeta\omega_n s + \omega_n^2} = A \frac{(s + \zeta\omega_n) + (1/\tau_1 - \zeta\omega_n)}{(s + \zeta\omega_n)^2 + \omega_n^2(1 - \zeta^2)}$$

The inverse Laplace transform is

$$e(t) = A e^{-\zeta\omega_n t} \left\{ \cos[\sqrt{\omega_n^2(1 - \zeta^2)} t] + \frac{1/\tau_1 - \zeta\omega_n}{\sqrt{\omega_n^2(1 - \zeta^2)}} \sin[\sqrt{\omega_n^2(1 - \zeta^2)} t] \right\}, \quad t \geq 0$$

(b) For a ramp of slope  $B$ ,  $T_d(s)/T_c = B/s^2$  which gives for  $E(s)$  the following:

$$\begin{aligned} E(s) &= \frac{B(s + 1/\tau_1)}{s(s^2 + 2\zeta\omega_n s + \omega_n^2)} = B \frac{\omega_n \sqrt{1 - \zeta^2} / \omega_n \sqrt{1 - \zeta^2}}{(s + \zeta\omega_n)^2 + \omega_n^2(1 - \zeta^2)} + \frac{B/\tau_1}{s(s^2 + 2\zeta\omega_n s + \omega_n^2)} \\ &= \frac{B}{\omega_n \sqrt{1 - \zeta^2}} \frac{\omega_n \sqrt{1 - \zeta^2}}{(s + \zeta\omega_n)^2 + \omega_n^2(1 - \zeta^2)} + \frac{B}{\tau_1 \omega_n^2} \left[ \frac{1}{s} - \frac{s + 2\zeta\omega_n}{(s + \zeta\omega_n)^2 + \omega_n^2(1 - \zeta^2)} \right] \end{aligned}$$

The inverse Laplace transform is

$$\begin{aligned} e(t) &= \frac{B}{\omega_n \sqrt{1 - \zeta^2}} e^{-\zeta\omega_n t} \sin(\sqrt{1 - \zeta^2} \omega_n t) \\ &+ \frac{B}{\tau_1 \omega_n^2} \left\{ 1 - e^{-\zeta\omega_n t} \left[ \cos(\sqrt{1 - \zeta^2} \omega_n t) + \frac{\zeta}{\sqrt{1 - \zeta^2}} \sin(\sqrt{1 - \zeta^2} \omega_n t) \right] \right\}, \quad t \geq 0 \end{aligned}$$

(c) The input  $T_d(t)/T_c = Ct^2 u(t)$  has Laplace transform  $T_d(s)/T_c = 2C/s^3$ . Partial fraction expansion gives the result

$$\begin{aligned} e(t) &= \frac{2C}{\omega_n^2} \left\{ 1 - e^{-\zeta\omega_n t} \left[ \cos(\sqrt{1 - \zeta^2} \omega_n t) + \frac{\zeta}{\sqrt{1 - \zeta^2}} \sin(\sqrt{1 - \zeta^2} \omega_n t) \right] \right. \\ &\left. + \frac{2C}{\tau_1 \omega_n^2} \left[ t + \frac{2\zeta}{\omega_n} + \frac{2\zeta}{\omega_n} e^{-\zeta\omega_n t} \cos(\sqrt{1 - \zeta^2} \omega_n t) + \frac{2\zeta^2 - 1}{\sqrt{1 - \zeta^2}} \sin(\sqrt{1 - \zeta^2} \omega_n t) \right] \right\}, \quad t \geq 0 \end{aligned}$$